SOCROB

Performance in Past Events

- Winner of the Scientific Challenge Award of the RoboCup 2000 Workshop with the paper "A Localization Method for a Soccer Robot Using a Vision-Based Omni-Directional Sensor", Carlos Marques, Pedro Lima
- Finalist paper of RoboCup Symposium 2007 Best Paper Award: 3D tracking by Catadioptric Vision Based on Particle Filters, Matteo Taiana, José Gaspar, Jacinto Nascimento, Alexandre Bernardino, Pedro Lima, Proc. of Robocup2007 - Robocup International Symposium, Atlanta, USA, 2007
- Qualified for the 2nd round-robin (top 8 teams) of RoboCup MSL 2003, 2004, 2006, and 2007
- 3rd place in EuRoboCup 2000, Amsterdam